## Data model of OpenDA

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Challenge the future

### "Context" of OpenDA

A generic toolbox for data-assimilation

- set of interfaces that define interactions between components
- library of data-assimilation algorithms
- OpenDA design goals:
  - Shared tools to reduce implementation costs
  - Shared knowledge between applications
  - Development of algorithms with eg universities
  - Easier to test, which should result in fewer bugs
  - Applications are configurable without recompiling
  - Portable to common platforms (windows, apple, linux)
  - "good" performance



#### Background, component based system

- Object oriented concepts
  - No direct access to data like Fortran arrays
  - Functions for all kinds of operations
- Main objects
  - Model instance (X,U,P)
  - (Tree)Vector
  - Stochastic Observer
  - Data Assmilation or Calibration method





#### TreeVector



- Ordering/distribution of data:
  - nodes (sub-TreeVector)
  - Leafs contain the values
- BLAS methods implemented e.g.
  - y=y+alpha x
  - dot=<y,y>
  - etc
- Values:
  - In memory
  - On (NetCDF) file
  - Distributed (parallel computing)
- Meta data (optional)
  - (simple) automatic interpolation (e.g. noise param)
  - Post processing





#### Model

- Internal model state
  - State (x)
  - Forcings (u)
  - Parameters (p)
- Direct operations on internal state
  - model.axpyState(alpha,dx)
- Interpolation Hx is method of the model: Hx=Model.getObsvalues(observer)
- Internal representation of x,u and p is up to the model programmer (java, Fotran, C, file).
- Note: formal model state (for restart etc) can contain (much) more data than the state used for filtering!





# Why hiding and stacking the data?

- Modularity of model
  - Extend model with a noise model
  - Extending (stochastic) model with a smoother
  - Automatic parallelization of model steps
  - No difference between parallel and sequential model
- Hide parallel computing
- Combine components from different languages
- Goal:
  - Flexible model configuration and extension (without need to change the deterministic models

DA

Method

Smoother

Model

Noise

Model

Deterministic

Model

Single implementation of DA method for all situations



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#### Observations

- Stochastic Observer
  - Observations
  - Meta information (about, time, location quantity, interpol kernel)
  - Uncertainty
- A bit similar to a relational database
- Selections based on time interval, location etc are possible
- Values are available as (tree) vectors

